T300 technology board¹)

The T300 technology board can be used to create technological functions for various applications such as:

- closed-loop tension and position control
- winders
- coilers
- synchronous and positioning control

hoisting drives

• drive-related control functions.

1) Attention! Only for compact and chassis units.

SIMOVERT MASTERDRIVES Vector Control Compact and Chassis Units

supplementa-

Electronics options		cifies which eeded to		Jompa	act and ch					
T300 technology board · Compone	pection is any and the function is drive function is									
Ordering information The selection The selection		e multi-motor ann are listoca. e multi-motor which are required. A products which are required. or drive column are required.		Components required for the standard software package				Components required for self-generated application software, using		
Product description	Comment	Order No.	Multi- motor drive	Axial winder	Angular syn- chronous control	Posi- tioning control	STRUC L	G STRUC		
T300 technology board with two SC58 and SC60 connecting cables, SE300 terminal block and G/E hardware instruction manual	German/English	6SE7090-0XX87-4AH0	•	•	•	•	•	•		
T300 technology boards as spare part		6SE7090-0XX84-0AH2	•	•	•	•	•	•		
LBA local bus adapter for MASTERDRIVES electronics box	Also used to install a communication board	6SE7090-0XX84-4HA0	•	•	•	•	•	•		
Additional instruction manual for the T300 hardware	German/English French	6SE7087-6CX84-0AH1 6SE7087-7CX84-0AH1								
Standard software package, multi-motor drive on an MS360 memory module without manual		6SE7098-6XX84-0AH0	•							
Manual, multi-motor drive ²)	German English	6SE7080-0CX84-6AH1 6SE7087-6CX84-6AH1	•							
Multi-motor drive standard softw. package on floppy disk in STRUC source code ³) MD360		6SW1798-6XX84-0AH0								
Standard software package, axial winder on an MS320 memory module, without manual		6SE7098-2XX84-0AH0		•						
Manual, axial winder ²)	German English	6SE7080-0CX84-2AH1 6SE7087-6CX84-2AH1		•						
Axial winder standard software package on floppy disk in STRUC source code ³) MD320		6SW1798-2XX84-0AH0								
Standard software package, angular synchronous control ⁴) on an MS340 memory module without manual		6SE7098-4XX84-0AH0			•					
Manual, angular synchronous control ²)	German English French	6SE7080–0CX84–4AH1 6SE7087–6CX84–4AH1 6SE7087–7CX84–4AH1			•					
Angular synchronous control standard software package on floppy disk in STRUC source code ³) MD340		6SW1798-4XX84-0AH0								
Standard software package, positioning control on an MS380 memory module without manual		6SE7098-8XX84-0AH0				•				
Manual, positioning control ²)	German English	6SE7080-0CX84-8AH1 6SE7087-6CX84-8AH1				•				
Standard software package, positioning control on floppy disk in STRUC® source code ³) MD380		6SW1798-8XX84-0AH0								
Generation software and accessories	for configuring (see Cat	alog ST DA)								
STRUC G/L Version 4.2 on CD-ROM with the Service IBS start-up program	See the text	-								
Configuring PC for STRUC G PT, installed	German/English See the text	6DD1801-1DA2						•		
ready to run Empty MS300 memory module for T300.	MS300	6SE7098-0XX84-0AH0					•	•		
8 Kbytes EEPROM Empty MS301 memory module for T300.	or MS301	6SE7098-0XX84-0AH1					•	•		
8 Kbytes EEPROM										
Parallel programming unit PPX1, external programming unit, for connection to a printer port with power supply unit (for PC/PG) with UP3 progr. Adapter	and G PT	6DD1672-0AD0					•	•		
PG7x0 connecting cable to T300 if Service IBS start-up program is used ¹)	Self-assembly according to the T300 instruction manual	-					•	•		
PC-AT connecting cable to T300 if Service IBS start-up program is used ¹)	Self-assembly according to the T300 instruction manual	-					•	•		

Depending on whether a SIMATIC-PG or a standard PC is used for start-up only one of the two cables is required.

2) Order the required number of manuals in the desired language, irrespective of the number of T300 standard software packages which have been ordered.

Only required if the standard is to be changed; requires STRUC configuring software.

4) The standard software package is only required for the slave drive(s). Example: Two drives which operate in angular synchronism: One standard software package for angular synchronous control is required.

SIMOVERT MASTERDRIVES Vector Control Engineering Information



Technology

Technology applications with the T300

The T300 can be used to provide additional technological functions for compact and chassis units (e.g. for closedloop tension and position control, coilers, winders, closed-loop synchronous and positioning controls, transverse cutters, hoisting equipment and drive-related control functions). Supplementary technological functions which are often requested are offered as standard software packages on pre-programmed memory modules.

The T300 and SIMADYN[®] D are fully compatible with each other.

Users who wish to create special applications or who wish to market their own technological know-how can create their own technological design on the T300 by using the graphics-oriented STRUC[®] planning language known from the SIMADYN D system.

Fig. 6/78 shows the most important hardware functions of the T300.

The technological functions are configured with STRUC and cyclically executed by the processor. The closedloop control sampling time is a minimum of 1 ms (see Catalog ST DA).

An overview of the hardware and software components of the T300 is provided in Fig. 6/79.

An almost delay-free parallel interface (dual-port RAM) permits data transfer between the basic unit and the T300. The serial connections can be directly connected to terminals on the T300. All other external signals can be connected at the SE300 terminal block outside the base unit. 15 V / 100 mA for supplying pulses is available at SE300 (see Fig. 6/78).

An external 24 V DC power supply must be provided if binary inputs and outputs have to be controlled. The base unit can also provide this voltage supply as long as the total current at terminals X101.13, 23 of the base unit is < 150 mA.

The software package is parameterized – irrespective of which software package is used – with the help of the following:

- a Drive ES or DriveMonitor PC
- the PMU operator control and parameterizing unit
- the OP1S user-friendly control unit
- an interface board (CBP, SCB1, SCB2)
- via an interface of the T300 with the service start-up program.

Altered parameters can be stored in the EEPROM (non-volatile).



Fig. 6/77 T300 board with memory module